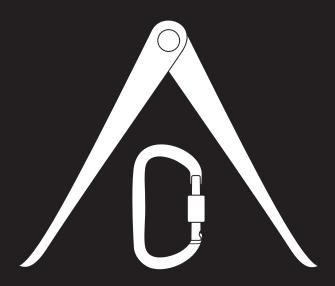
CLIMBING TECHNICAL



www.climbingtechnical.com

IG: CLIMBING TECHNICAL

Climbing Technical is driven by James Smith, he has worked around the world across multiple Working at Height Industries. As well as working as an arborist James has over 10 years experience within the film industry as a stunt rigger and performer working in New Zealand, Fiji, China and India. Regardless of industry or setting his primary concern has been the safety of others while at height and the duty of care that comes with it.

Climbing Technical's design and illustration side has grown out of the documentation that James found was lacking within the film industry and difficulties in conveying the often complex nature of rigging setups. When looking at the user instructions that came with climbing and rigging equipment he saw an example of how illustration could be used to communicate how systems worked and worked on creating a system which replicates and expands on this. The result is Climbing Technical and the extensive library of resources that the company can now draw on to help communicate working at height systems with people regardless of ability, language or experience.

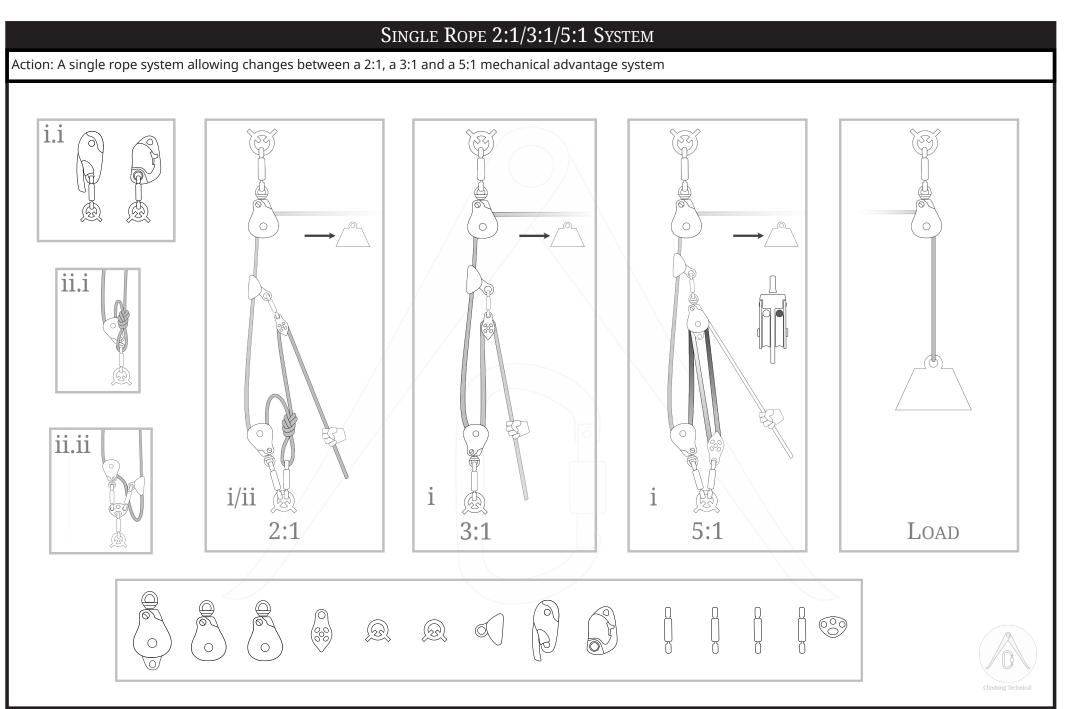
A full list of projects that Climbing Technical has been involved in is available on request. Pricing of projects is done on a job by job quote basis that is tailored to each companies needs and budgets.

Samples:

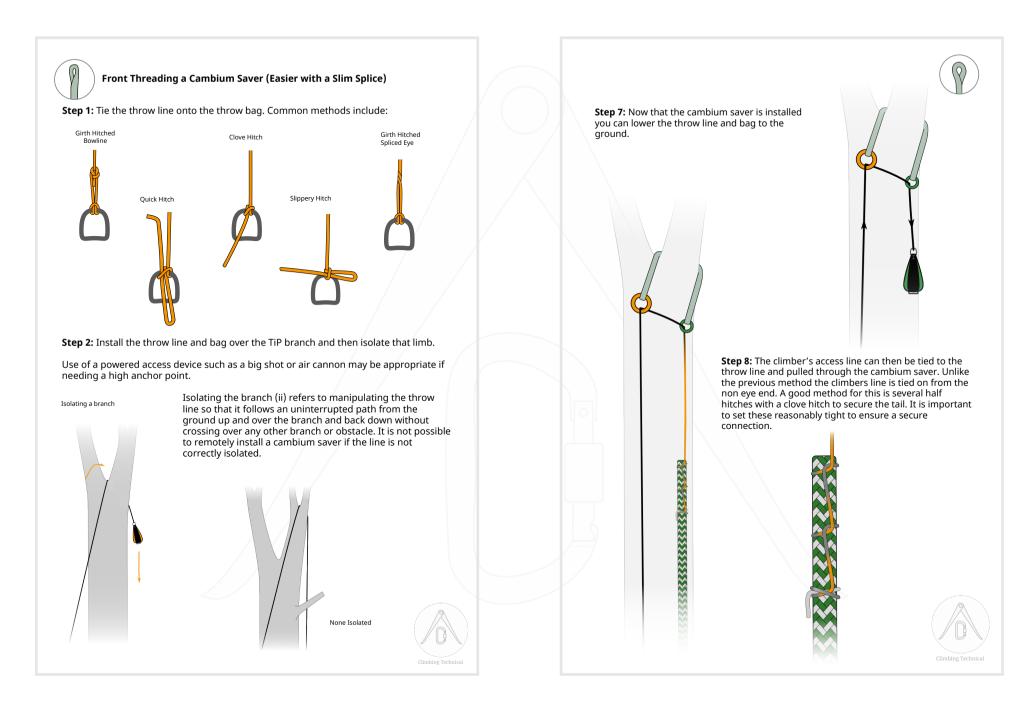
i: Single Rope 2,3,5:1 System Illustration ii-iii: Educational Articles samples iv: Professional Development Bulletin v: Client Work vi: User Manual Concept vii: Other samples

For more educational content see the climbing.technical instagram page.

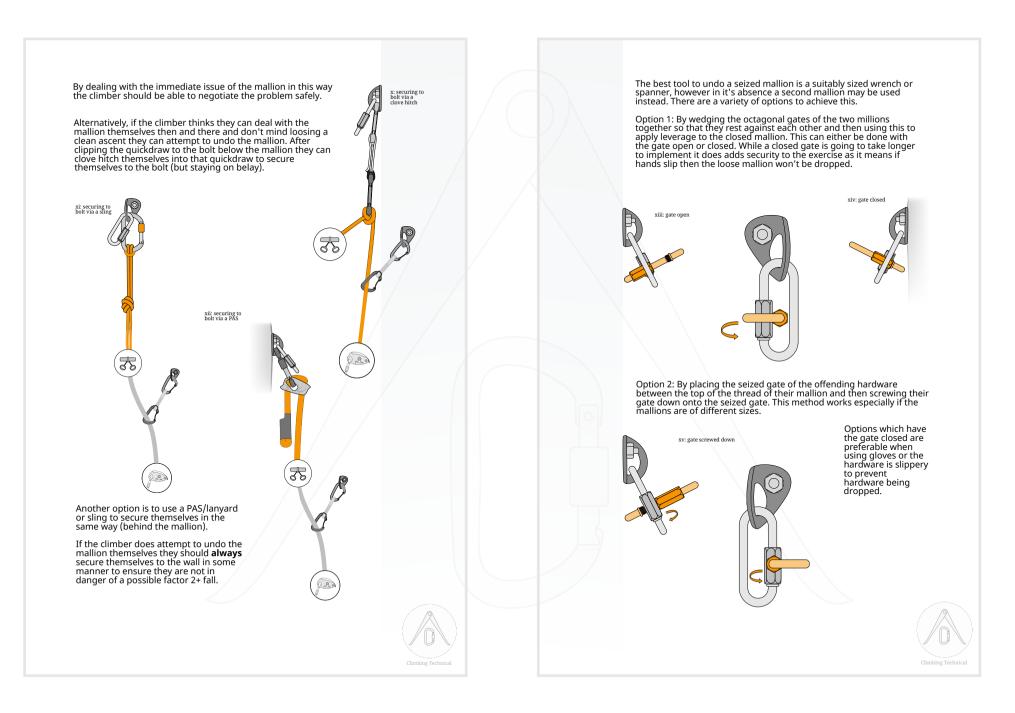
i. Rigging Illustration Sample



ii. EDUCATIONAL ARTICLE SAMPLE - REMOTE CAMBIUM SAVER INSTALL



iii. EDUCATIONAL ARTICLE SAMPLE - MALLIONS ON SPORT CLIMBING BOLTS

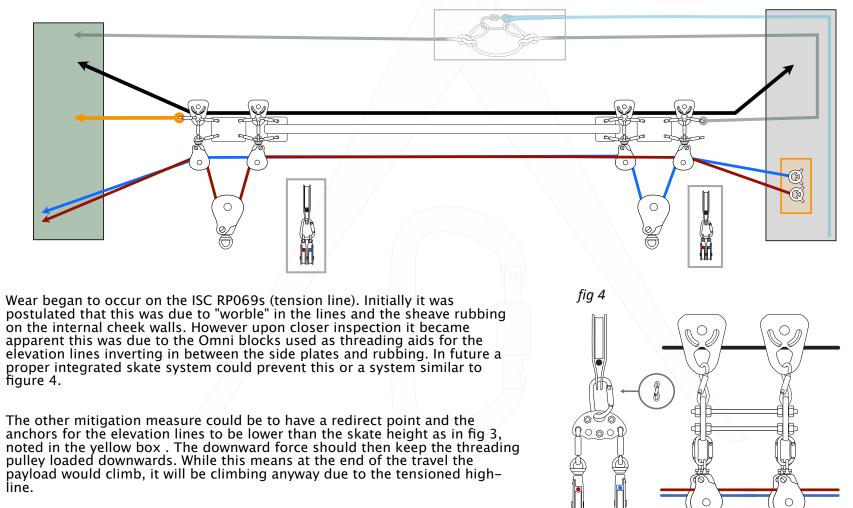


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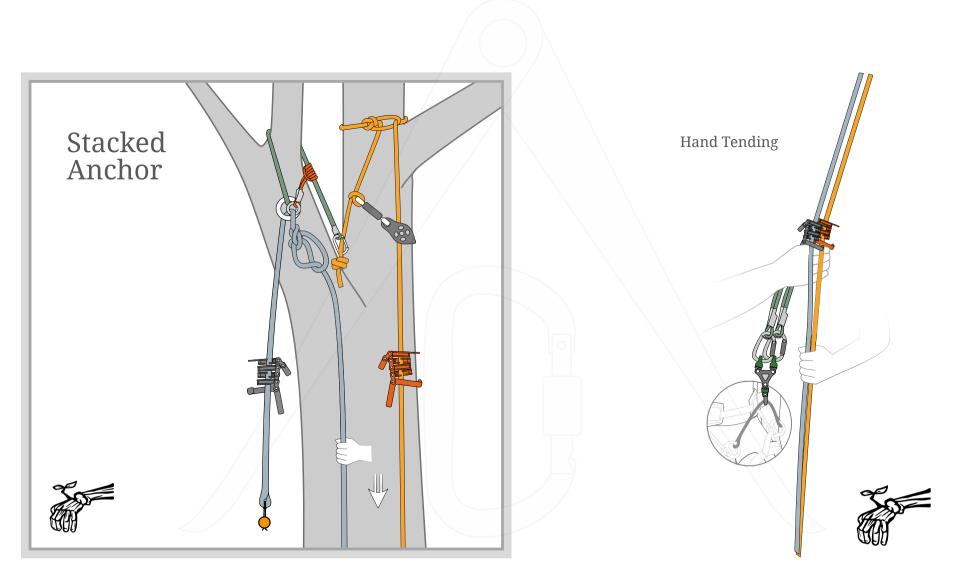
AFTER ACTION REPORT - REF: PV SHOOT

Skate: See fig 3 for recommended changes. The internal 2:1s were found to be too far apart and meant that as the payload was raised to the max height it became exponentially harder in last 20% of the move as the angle flatted out. Furthermore by not hard locking the components together this meant they would move and settle which created lag in the system.

fig 3 (consult page 3 of PV Rig Plans for full plan)

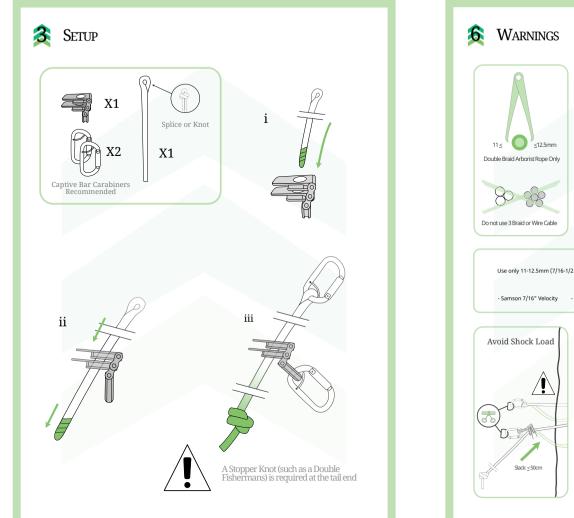


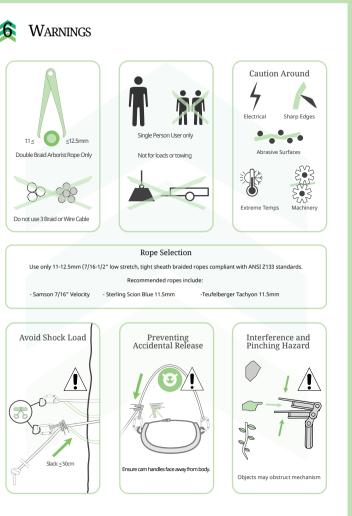
V. CLIENT WORK - EDUCATIONAL DIAGRAMS FOR PAUL POYNTER - ALL RIGHTS REMAIN WITH PAUL/WOODEN HAND.





vi. USER MANUAL CONCEPT (UNRELEASED) - Personal Project















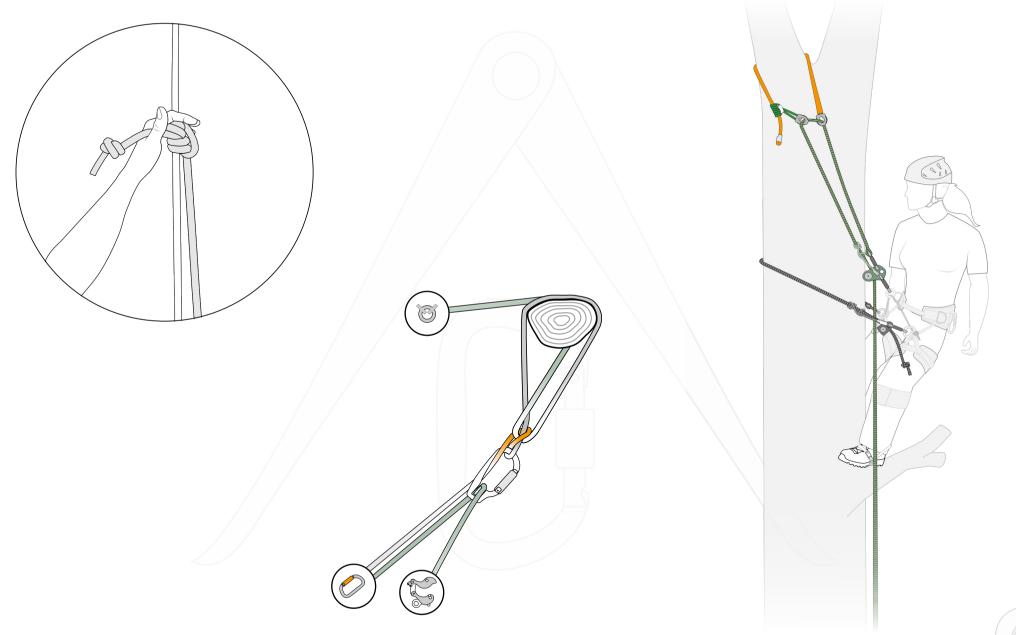








vii. Other Samples







climbing.technical



james@climbingtechnical.com



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